## Kongsberg DGNSS infrastructure solutions

#### **General Overview**

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## **DGNSS Service**

- The DGNSS service was established in order to improve safety and efficiency of navigation
- More than 300 reference stations (IALA) in operation around the world
- The removal of Selective Availability (SA) in year 2000 did not remove the requirement for GNSS augmentation
- Without augmentation GNSS accuracy may contain significant errors for extended periods of time and no integrity information is provided



# 

# Definitions

#### >Availability (ref. IMO Res. A860)

The percentage of time that an aid, or system of aids, is performing a required function under stated conditions. The non-availability can be caused by scheduled and/or unscheduled interruptions

#### Continuity/reliability

 Continuity is the ability of a system to function within specified performance limits without interruption during a specified period (normally short term)

#### >Integrity

 Integrity is the ability to provide users with warnings within a specified time when the system should not be used for navigation

#### >Accuracy

✓ Absolute horizontal accuracy should be better than 10m (95%) inside the coverage area. 1m at the reference station. Degradation around 1m pr 150km from the broadcast site



## **System characteristics**

- The International Maritime Organisation (IMO) issued a performance standard, IMO A.815(19) in 1995, containing the main system characteristics.
- The resolution A.815(19) was revoked by A.953 (23) in 2004 and provides standards for accuracy, availability and continuity from a satellite radio navigation system.
- ≻ Technical parameters of IALA DGNSS, ref A.953;

Position Accuracy:	10m (95%)
Availability - Coastal/harbor with low level of risk - Coastal/harbor with high level of risk	Calculation; IALA Rec. R-121 >99.5% over 2 years >99.8% over 2 years
Reliability/continuity - Coastal/harbor with low level of risk - Coastal/harbor with high level of risk	≥99.85% over 3 hours ≥99.97% over 3 hours
Integrity	Time to Alarm less than 10 sec



### **Technical parameters**

The transmission of the DGNSS correction and integrity data are based on the ITU-R.M 823-2 (message format).

>The main technical characteristics of the IALA DGNSS beacons are;

Frequency band	283.5 – 315.0 kHz in Europe 283.5 – 325.0 kHz in other regions
Modulation	Minimum Shift Keying (MSK)
Data Rate	50, 100 or 200 Bit/s. Since S/A has been removed most countries use 100/200 Bit/s
Data Format	RTCM SC104 V 2.3 Messages for DGPS Messages available for DGLONASS V 2.4 on draft autumn 2009 embracing new satellite navigation systems as well
International Standard	ITU- Recommendation M. 823-2



## **Standards and recommendations**

- IMO A. 815(19) states main system characteristics. Accuracy, availability, reliability and integrity. Revoked by A.953(23).
- IALA Recommendation R-121, the performance and monitoring of DGNSS services in the frequency band 283,5 – 325 kHz, Edition 2.0, May 2015.
- IALA Guideline No. 1112, the performance and monitoring of DGNSS services in the frequency band 283,5 – 325 kHz, Edition 1, May 2015
  - ✓ Performance and monitoring requirements for a DGNSS system.
- > ITU-R M.823-2 states the message format and transmission characteristics.
- ▶ RTCM SC104 v2.3 states the RTCM message data format.
  - $\checkmark$  V2.4 on draft level autumn 2009 and is introducing significant changes.
- RTCM SC104 RSIM v 1.2- outlines the performance, functional, interface, and environmental parameters for DGPS reference stations, integrity monitors and transmitter/RSIM interface modules.

## **Kongsberg DGNSS infrastructure**





#### DGNSS REFERENCE AND INTEGRITY MONITORING STATIONS

DRS 500 and IMS 500 are the third generation DGNSS reference products from Kongsberg Seatex. The products feature a new graphical user interface for real time operation and system control. The new Huma Machime interface (HM) is optimised for easy detinitization <i>d</i> , and fast operator response to events. The
DRS 500 and IMS 500 are fitted with a state-of-the art GNSS receiver supporting future signals in space.

In a DGNES nateork infrastructure, the DRS 500 and the IMS 500 are Integrated enabling both pre and poel Integrity control. A Central Monton application (DGNSS CAI) enables full remote operation of all stations in a network.	The RTCM data will be checked for availability, position a caracy and other quality orteria. Alarms and warnings will displayed and stored in an alarm file. Based on predefine orteria, the IMS 500 will switch between the two DRS 500 in a redundent confloaration.
DR9 500	
The DRS 500 is a DONSS reference station designed for	Transmitters

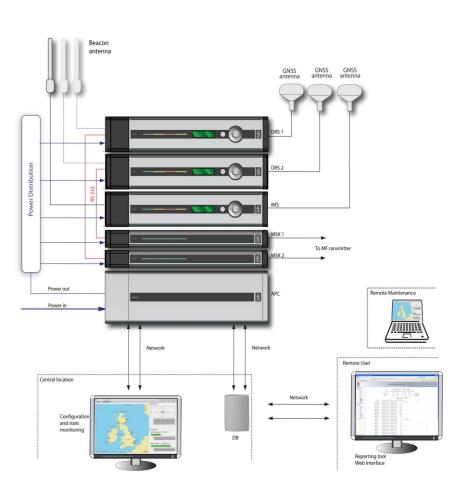


#### **DGNSS Central Monitor**

#### OPERATION OF DOMES INFRASTRUCTUR

critor (CM) is a software application developed to provide a complete solution for the utilisa ISS reference station and integrity monitor for navigation. The application offers full remote review over configuration and status parameters for an unlimited number of DGNSS value.

In a DGNES network inflastructure, the Central Montor oper- alies together with a DRS 300 (Differential Reference Batton) and an MB 300 (Integrity Montos Stationy in a TCH/M network. Several reference stations, the field stations and central moni- tors may coinsis in the same network.	ONESS integrity inheating and monitoring     System components monitoring     Roads transmission quality monitoring     Roads configuration of indexnoce station and integrity monitor     Pleconding of indexnoce station integrity data and performance
	statutics in a datatuse
System features	<ul> <li>Alarm handling</li> </ul>
The main objective of the CM application is to provide toxia for remote control, monitoring, data collection and on-line quality.	- Storing of alarms and data
control of a metwork of DIGNIDS reference stations. The product	Network
features a new graphical user interface for real-time operation and system control. The primary goal of the new HMI (Human Machine Interface) is for the operator to identify and react to critical situations effectively and safety.	The CM application uses a TCP-IP based network infrastruc- ture. Each and at the relevance station values and fair field monitor shirs, has its own unique IP address and the data is starstered detectly from the sites to the Central Monitor. The originating IP address of the data is used to identify the source of the data to
The system features include: • System performance status monitoring • Early warring to operators if performance is outside threatests • Continuous recording of differential corrections and data from the reference stations	The applications and territors in the CM application software. To simplify the management and configuration, a Data Houter is used to make and encapsulate the data internaty in the meteoris, making it possible to concentrate the data into a single TCP or UCP network data stream.



#### **MSK 500**



#### MSK MODULATOR

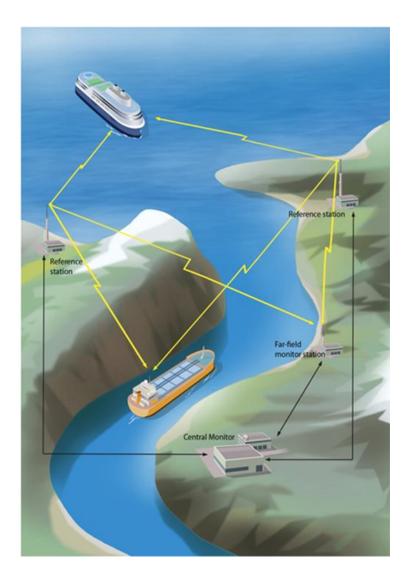
The Kongeberg MSK 500 (Mexmun SMR Keying) modulator is designed specifically to work with marine DGMSS radio beacon systems.	The MSK herp MSK 500 is a maintenance. RS, 232 istacto
The MSK 500 receives otherential GNSS corrections from the DMS 500 reference station and transfers corrections to the transmitter for broadcast on mediam heparroy (MP) to sur- monther user.	through the Di site or nettotal

ECHNICAL DATA		POWER SPECIFICATIO	NS
Dala rate	9600 hms	Voltage	24 V DC (18 to 30 V DC)
requency range requency resolution	283.5 to 325.0 kHz 500 Hz	Power consumption	Max. 25 W
requercy stability interaction rate of MSK	#2.0 x 10 <sup>4</sup>	ENVIRONMENTAL SPE Temperature range	CIFICATIONS
nodulation Subsul voltage into	50, 100, 200 kpa	Operating temperature	-15 °C to +55 °C?
i0 Ohma	0.5±0.1V	Humidity Operating humidity	Max. 95 % non-condenants
STERFACE SPECIFICA	ATIONS		
100	85-222	Electromagnetic comp	atibility
F output connector	N-female.	Immunityhadication	IEC 80945/EN 80945
EIGHTS AND DIMEN	SIONS	PRODUCT SAPETY	
ESK Lind devenations	450 mm x 44 mm x 205 mm	Low voltage	IEC 60950-1/EN 60950-1
ASK Link weight	2.5 kg	Accommanded *	



# **System Architecture**

- IP based network infrastructure.
- Continuously monitoring of reference and far field stations from CM, incl. alarm management.
- Automatic database update if line of communications are down
- Autonomus operation of reference stations even though lines of communication to central is down.
- All sites are remotely operated from Central Monitor.



# **DGNSS Network Components, overview**

#### Hardware modules

The following modules are typical components on a reference site. Redundancy is achieved by great flexibility in HW.

✓ DRS 500, Reference station
 ✓ IMS 500, Integrity Monitoring
 ✓ APC 500, Power Control Unit
 ✓ MSK 500, Minimum Shift Keying (MSK) modulator
 ✓ Keyboard and display and KVM switch

✓ Using Southern Avionics (SAC) MF radio systems

#### Software Modules, Control Center

✓ DGNSS network, Central Monitor (CM)✓ DGNSS network, Reporting Tool

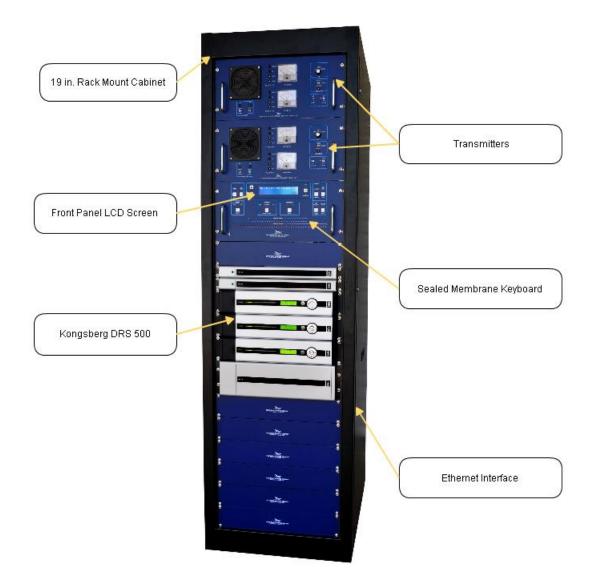
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## **Southern Avionics MF Radio System**



16.02.2022



## **Southern Avionics MF Radio System**

FEATURE	SPECIFICATION
Frequency	283.5 - 325 kHz 5 mW MSK sinewave signal
Power Output	Carrier power into 50 Ohms continuously adjustable from 10 - 500 W max
Spurious Emission	Less than -70 dBc
Radiated Harmonics	Less than -60 dBc
Type of Emission	NON, G1D
Noise and Hum Level	Less than -40 dB
Input Power	115/230 V +/-10%, single phase 50 - 60 Hz; or 144 VDC or both with switch over to batteries
Nominal AC input power	688 W at 500 W output
Nominal DC input power	575 W at 500 W output
Temperature Range for Working Conditions	-15°C - +55°C
Relative Humidity for Working Conditions	0 - 95%
Metering	Forward power output, reflected power output, PA voltage and PA current
Height	78 in. (198cm)
Length	32 in. (81cm)
Width	23 in. (58cm)
Temperature Range for Working Conditions	-15°C - +55°C



#### KONGSBERG KONGSBERG DRS 500

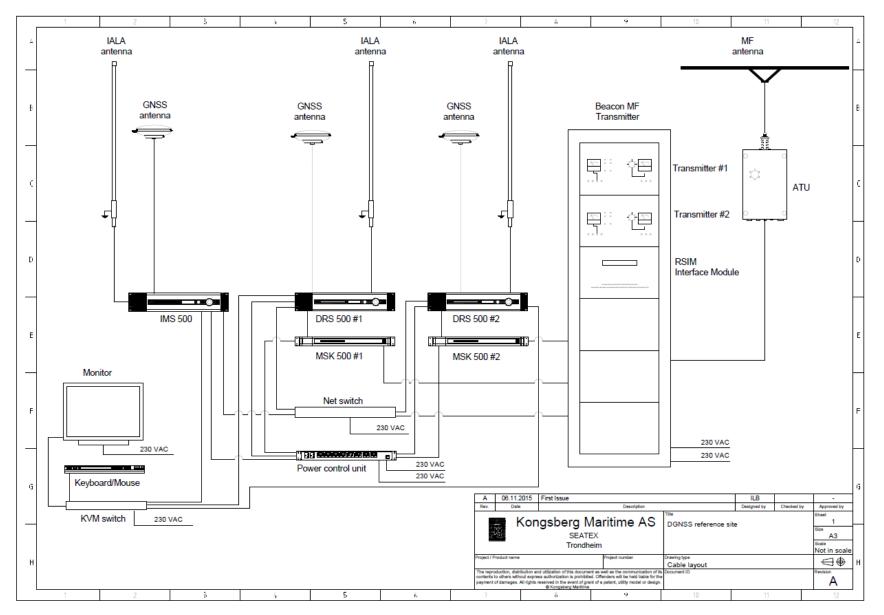
The KONGSBERG IMS 500 is a DGNSS integrity monitor station designed for permanent installations as a stand-alone system or as part of national or regional GNSS infrastructure systems. The electronic components are built into a 19-inch rack module and all components are fully remotely operated. The software offers full control and overview of configuration and status parameters in an intuitive graphical user interface.

#### Features and Performance

- RTCM corrections at up to 2Hz on 4 independent ports
- Sub-metre position achievable with high quality roving unit
- RTCM ver. 3.0
- Standard RTCM GPS corrections, type 1, 2, 3, 5, 6, 7, 9, 16, 27
- GPS RTK corrections, RTCM type 18, 19, 20, 21
- GLONASS corrections, RTCM type 31 and 32
- RSIM messages for integrity monitoring
- Full remote control by direct or dialup connection
- Storage of raw-data for postprocessing



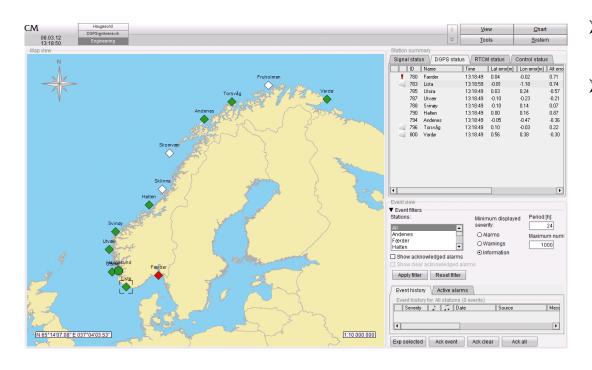
### **Architecture example – Reference Site**





# **Central Monitor**

- The Central Monitor (CM) is an application developed to provide a complete solution for the utilization of the DGNSS reference station and integrity monitor.
- CM offers full remote control and overview over configuration and status parameters for an unlimited number of DGNSS reference stations and integrity monitor stations.



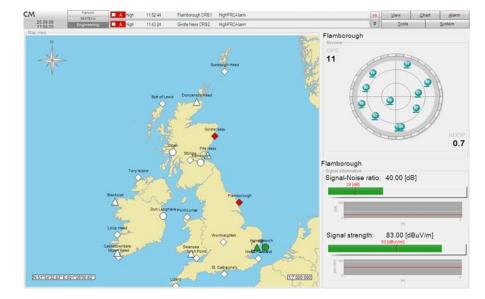
- Tailored for real time operation and service with special focus on:
  - ✓ Status and system integrity
  - ✓ Efficient operation and remote maintenance
  - ✓ User friendlyness
- User interface developed in close co-operation with end users
- Local user interfaces (DRS/IMS) are built upon the same principles as the CM in order to ease the training and day to day operation





# Main Objectivities of the CM

- GNSS integrity checking and monitoring
- System components monitoring (e.g. Mimic diagram)
- Radio transmission quality monitoring
- System performance status monitoring
- Early warning if performance is outside thresholds
- ≻Alarm system
- Alarms and RSIM data stored in central DB. Raw data stored locally
- Remote configuration of equipment at reference and FFM sites
- Tool for automatic verification and reporting of system performance

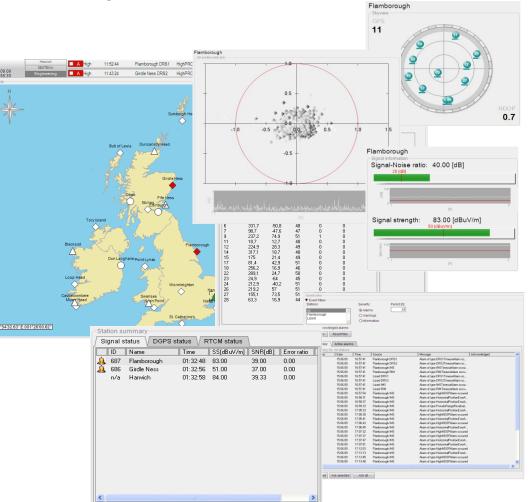




## Views

The operator may select between the following views:

- ≻Map view
- ➤Satellite status view
- ≻Sky view
- >2D position plots
- Reference station correction data
- ➢Signal information
- ►IMS correction data
- Mimic status diagram
- ➢RIM information view
- ➤Event view
- ➤Active alarms view
- ➤Station summary which includes:
  - ✓ Signal status view
  - ✓ DGPS status view
  - ✓ RTCM status view





## Configuration

All configurations for the different sites and units may be carried out remotely via the CM. Alarm settings are also managed from the configuration view.

System Configuration X			
Station configuration V CM configuration V Monitored stations V Alarms V Disable alarm	IS		
Flamborough         Girdle Ness         Lizard         St. Catherine's         Wormleighton         BSR         Alarm thresholds         RTCM Configuration         BRSN scheduel         DRS2         Alarm thresholds         RTCM Configuration         BRSN scheduel         DRS2         Alarm thresholds         RTCM Configuration         BRSN scheduel         IMS         Alarms         Demodulator         BRSN scheduel         Failed to load RIM config	<ul> <li>Mimimum sattelites alarm Minimum sattelites</li> <li>Obervation interval</li> <li>PRC alarm</li> <li>Obervation interval</li> <li>PRC alarm threshold</li> <li>RRC alarm</li> </ul>	12 4 60 500 60 4 4 	
		<u>S</u> ave <u>C</u> lose	

## Web reporting tool

Done



#### **Monthly report** Select station(s) Select year Sample mode 2013 AII. Ŧ Instantaneous Makis Select month O Hourly mean February Generate report Monthly report - February, 2013 Accuracy Availability Integrity MTBF MTTR Outages Continuity Charts Station [m] [%] [#] [hours] [hours] [#] [%] Makis 0.392 99.79 0 0.70 2 708.00 99.58 2D SS SNR SVs Continuity is the ability of a system to function within specified performance limits without interruption during a specified time interval (normally 3 hours). Continuity considers overlapping coverage and ignores planned outages, and is based on last 24 months (rolling). The MTBF/MTTR values are based on last 12 months (rolling). Outages Duration Station Planned Cause Date start Time start Date end Time end Comment [sec] 27/02/2013 14:24:05 27/02/2013 15:34:40 Makis. 4234 Zero signal strength Makis 27/02/2013 15:42:06 27/02/2013 15:55:15 789 Zero signal strength Total planned outage: 0 seconds. Total unplanned outage: 5023 seconds. Report was generated using all samples. 😪 Local intranet Done Done - 🔩 90% 🔹

#### References



#### **DGNSS Infrastructure, latest generation product range**

- UK and Ireland
  - 14 + 3 x Reference Station sites
  - 6 x Far-field stations
- Norway
  - 12 x Reference Station Sites
  - 8 x Far-field Stations
- Belgium
  - 1 x Reference Station Site
  - 1 x Far-field Stations
- Serbia
  - 1 x Reference Station Site
  - 2 x Far-field Stations
- Malaysia
  - 2 x Reference Station Sites
  - 2 x Far-field Stations



#### November 2015

- The Netherlands
  - 3 x Reference Station Sites 3 x Far-field Stations



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